

What's new in dune-functions?

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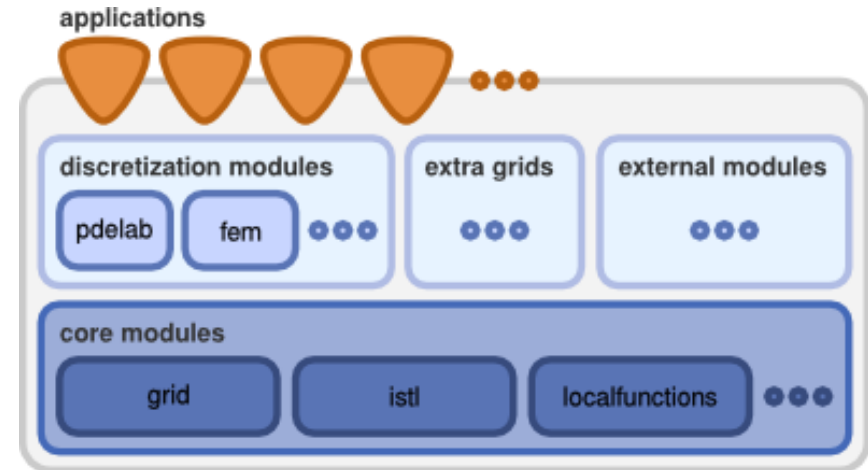
FAU Erlangen–Nürnberg, Department Mathematik

Dune user meeting 2023

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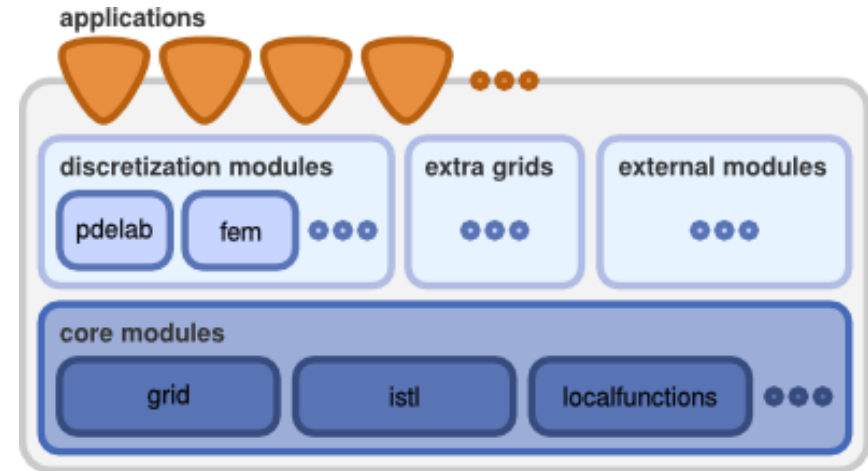
Core modules

- dune-common
- dune-geometry
- dune-grid
- dune-localfunctions
- dune-istl



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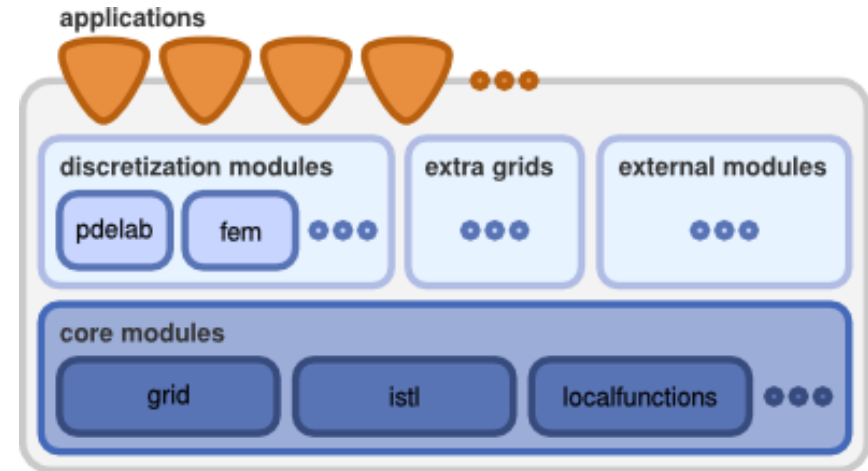


What's missing?

- Interfaces for (differentiable, grid, ...) functions
- Global function space bases
- Local and global assembler framework
- Definition of variational problems
- ...

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What's missing?

- Interfaces for (differentiable, grid, ...) functions
- Global function space bases
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This is what dune-functions deals with.

Dune-functions history

- Initiated by Engwer, Müthing, Sander, G.
- First commit '13
- First release '16

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Dune core history

- First commit '03
- First release '07

Dune-functions history

- Initiated by Engwer, Müthing, Sander, G.
- First commit '13
- First release '16
- 10 years of dune-functions!

Dune core history

- First commit '03
- First release '07
- 20 years of dune!



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Aims of dune-functions

- Unified interfaces of functions and function space bases
- Shared efforts between discretization modules
- Discretization modules using dune-functions
 - Dune-pdelab, dune-fufem, Amdis, ...

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Design principles and techniques

- Flexible and efficient interfaces
- Modern and lightweight design
- Duck typing, type deduction, concepts, ...

Global function interface

```
auto y = f(x);  
std::function<Range(Domain)> g = f;
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Differentiable function interface

```
auto df = derivative(f);  
auto y = df(x);
```

```
DifferentiableFunction<Range(Domain)> g = f;
```

```
auto dg = derivative(g);  
auto y = df(x);
```

Global function interface

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auto y = f(x);  
std::function<Range(Domain)> g = f;
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Differentiable function interface

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auto df = derivative(f);  
auto y = df(x);
```

```
DifferentiableFunction<Range(Domain)> g = f;
```

```
auto dg = derivative(g);  
auto y = df(x);
```

Grid function interface

```
auto f_local = localFunction(f);  
f_local.bind(element);  
auto y = f_local(x_local);
```

```
GridViewFunction<Range(Domain), GridView> g = f;
```

```
auto g_local = localFunction(g);  
f_local.bind(element);  
auto z = g_local(x_local);
```

The interface for functions in the dune-functions module. (Engwer/G./Müthing/Sander '17)

Nested basis interface

Create a nested basis:

```
using namespace Dune::Functions::BasisFactory;
auto basis = makeBasis(gridView,
    composite(
        power<dim>(
            lagrange<2>()),
        lagrange<1>()));
```

Using the basis:

```
auto localView = basis.localView();
for(const auto& element: Dune::elements(gridView))
{
    // Bind to a grid element
    localView.bind(element);

    // Obtain finite element from ansatz tree
    auto&& velocityFE = localView.tree().child(_0, 0).finiteElement();
    auto&& pressureFE = localView.tree().child(_1).finiteElement();

    // Local element-wise index of basis function
    auto&& localIndex = localView.tree().child(_0, 0).localIndex(k);

    // Global index of basis function
    auto&& globalIndex = localView.index(localIndex);
}
```

Function space bases in the dune-functions module. (Engwer/G./Müthing/Sander '18)

Nested bases

- Bases can be nested using two constructions:
 - Composite product spaces $V_0 \times V_1 \times \cdots \times V_m$
 - Power spaces $V^k = V \times \cdots \times V$

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- Order and blocking of global indices can be influenced
 - Interleaved or lexicographic order
 - Blocked or flat indices
 - Custom reordering/blocking

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Currently implemented bases

- Lagrange, Langrange-DG, hierarchical P2, Rannacher-Turek
- BDM, Raviart-Thomas, B-splines

Report from 2003 meeting

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Main decisions on the meeting

- Export information on index blocking structure
- Implementation of Hermite bases
- Dynamic power spaces

Example: Various multi-index schemes for Taylor-Hood

- Each column represents an indexing scheme
- Different indexing schemes for different containers and algorithms

	BL(BL)	BL(BI)	BL(FL)	BL(FI)	FL(BL)	FL(BI)	FL(FL)	FL(FI)
$v_{x_0,0}$	(0, 0, 0)	(0, 0, 0)	(0, 0)	(0, 0 + 0)	(0, 0)	(0, 0)	(0)	(0 + 0)
$v_{x_0,1}$	(0, 0, 1)	(0, 1, 0)	(0, 1)	(0, 3 + 0)	(0, 1)	(1, 0)	(1)	(3 + 0)
$v_{x_0,2}$	(0, 0, 2)	(0, 2, 0)	(0, 2)	(0, 6 + 0)	(0, 2)	(2, 0)	(2)	(6 + 0)
$v_{x_0,3}$	(0, 0, 3)	(0, 3, 0)	(0, 3)	(0, 9 + 0)	(0, 3)	(3, 0)	(3)	(9 + 0)
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
$v_{x_1,0}$	(0, 1, 0)	(0, 0, 1)	(0, $n_2 + 0$)	(0, 0 + 1)	(1, 0)	(0, 1)	($n_2 + 0$)	(0 + 1)
$v_{x_1,1}$	(0, 1, 1)	(0, 1, 1)	(0, $n_2 + 1$)	(0, 3 + 1)	(1, 1)	(1, 1)	($n_2 + 1$)	(3 + 1)
$v_{x_1,2}$	(0, 1, 2)	(0, 2, 1)	(0, $n_2 + 2$)	(0, 6 + 1)	(1, 2)	(2, 1)	($n_2 + 2$)	(6 + 1)
$v_{x_1,3}$	(0, 1, 3)	(0, 3, 1)	(0, $n_2 + 3$)	(0, 9 + 1)	(1, 3)	(3, 1)	($n_2 + 3$)	(9 + 1)
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
$v_{x_2,0}$	(0, 2, 0)	(0, 0, 2)	(0, $2n_2 + 0$)	(0, 0 + 2)	(2, 0)	(0, 2)	($2n_2 + 0$)	(0 + 2)
$v_{x_2,1}$	(0, 2, 1)	(0, 1, 2)	(0, $2n_2 + 1$)	(0, 3 + 2)	(2, 1)	(1, 2)	($2n_2 + 1$)	(3 + 2)
$v_{x_2,2}$	(0, 2, 2)	(0, 2, 2)	(0, $2n_2 + 2$)	(0, 6 + 2)	(2, 2)	(2, 2)	($2n_2 + 2$)	(6 + 2)
$v_{x_2,3}$	(0, 2, 3)	(0, 3, 2)	(0, $2n_2 + 3$)	(0, 9 + 2)	(2, 3)	(3, 2)	($2n_2 + 3$)	(9 + 2)
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
p_0	(1, 0)	(1, 0)	(1, 0)	(1, 0)	(3 + 0)	($n_2 + 0$)	($3n_2 + 0$)	($3n_2 + 0$)
p_1	(1, 1)	(1, 1)	(1, 1)	(1, 1)	(3 + 1)	($n_2 + 1$)	($3n_2 + 1$)	($3n_2 + 1$)
p_2	(1, 2)	(1, 2)	(1, 2)	(1, 2)	(3 + 2)	($n_2 + 2$)	($3n_2 + 2$)	($3n_2 + 2$)
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots

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- How to properly export the index information?

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Implementation status

- Prototype exists
- Needs review and merge
- https://gitlab.dune-project.org/staging/dune-functions/-/merge_requests/350

Problem

- C^1 /Hermite bases cannot use plain affine transformations
- How to generically implement Hermite-type bases?

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Implementation status

- Prototype(s) exists
- Included implementations:
 - Hermite triangle, Morley, Agyris, and Arnold-Winther element
- Needs polishing and review
- https://gitlab.dune-project.org/staging/dune-functions/-/merge_requests/421

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- Power spaces V^k with run-time exponent k
- How to efficiently generate dynamically sized return values?

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auto x = f(y);
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Partial Solution

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Implementation status

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Multi-threading

- Interface is designed to localize mutable data
- For now no changes required
- Document thread safety guarantees

Caching of non-trivial bases

- How to implements evaluation caching of non-affine bases?
- Proper interface for cacheable information needed

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Future development

- Data model for distributed bases
- ...

Painless definition of local assemblers

- UFL-like language to describe variational forms
- No code generation, plain C++
- Automatic caching and sharing of shape function evaluations
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Example: Poisson-problem

```
auto u = trialFunction(basis);  
auto v = testFunction(basis);  
auto A = integrate(dot(grad(u), grad(v)));
```

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auto u = trialFunction(basis);
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```

Example: Mixed Poisson-problem

```
auto sigma = trialFunction(basis, _0, NonAffineFamiliy{});
auto u      = trialFunction(basis, _1);
auto tau    = testFunction(basis, _0, NonAffineFamiliy{});
auto v      = testFunction(basis, _1);

auto A = integrate(dot(sigma, tau) - div(tau)*u - div(sigma)*v);
```

```
// Explicitly denote subspaces of the mixed finite element space
auto velocityBasis = subspaceBasis(basis, _0);
auto pressureBasis = subspaceBasis(basis, _1);

// Define trial and test function spaces
auto u = trialFunction(velocityBasis);
auto p = trialFunction(pressureBasis);
auto v = testFunction(velocityBasis);
auto q = testFunction(pressureBasis);

auto f = Coefficient(rhsGridFunction);

// Initialize coefficient vector coeff
[...]
```

```
// Fixed point iteration
while ([...])
{
    // Previous iterate
    auto coeff_old = coeff;
    auto u_old = bindToCoefficients(u, coeff_old);

    // Define local assembler for 0seen problem with given advection
    auto A = integrate(nu*dot(grad(u),grad(v)) + dot(dot(u_old,grad(u)),v) + div(u)*q+div(v)*p);
    auto b = integrate(dot(f,v));

    // Call global assembler and linear solver
    [...]
```

```
}
```

Example: Primal plasticity with kinematic and isotropic hardening

```
// Basis with deformation, plastic tensor, and hardening variable
auto basis = makeBasis(grid.leafGridView(), composite(
    power<dim>(lagrange<1>()),
    power<k>(lagrange<0>()),
    lagrange<0>()));

// B is an isometry between  $R^k$  and the trace free symmetric matrices
auto B = RangeOperator([](const auto& p) {
    return 1.0/std::sqrt(2.0) * FieldMatrix<double,2,2>{{p[0], p[1]},{p[1], -p[0]}};
});

// Symmetric gradient
auto E = [&](const auto& v) { return symmetrize(grad(v)); };

// Elasticity tensor for isotropic material
auto C = RangeOperator([&](const auto& e) {
    return 2*mu*e + lambda*Id*trace(e);
});

// Trial and test function spaces
auto u   = trialFunction(basis, _0);
auto p   = trialFunction(basis, _1);
auto eta = trialFunction(basis, _2);
auto v   = testFunction(basis, _0);
auto q   = testFunction(basis, _1);
auto nu  = testFunction(basis, _2);

// Apply isometry to get matrix valued trial and test function spaces
auto P = B(p);
auto Q = B(q);

auto A = integrate(dot(C(E(u)-P),E(v)-Q) + k1*dot(P,Q) + k2*dot(eta,nu));
```

Features to come soon

- Export information on index blocking structure
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Getting started

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- Manuals on function and basis interfaces
- Examples with raw dune-functions

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Dune-functions based assemblers in dune-fufem

- If you're interested: Contact me.

Thank you for your attention.